



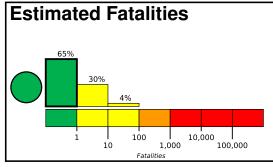


PAGER Version 7

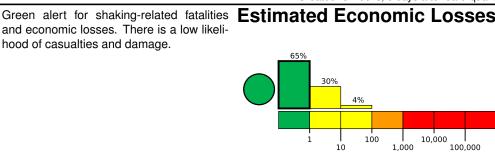
Created: 3 weeks, 6 days after earthquake

M 5.4, 10 km ESE of Yayladere, Turkey

Origin Time: 2021-06-25 18:28:37 UTC (Fri 21:28:37 local) Location: 39.1823° N 40.1726° E Depth: 7.3 km



and economic losses. There is a low likelihood of casualties and damage.



Estimated Population Exposed to Earthquake Shaking

							<u> </u>			
ESTIMATED POPULATION EXPOSURE (k=x1000)		_*	10,060k	406k	22k	2k	0	0	0	0
ESTIMATED MODIFIED MERCALLI INTENSITY		I	11-111	IV	V	VI	VII	VIII	IX	X+
PERCEIVE	SHAKING	Not felt	Weak	Light	Moderate	Strong	Very Strong	Severe	Violent	Extreme
POTENTIAL	Resistant Structures	None	None	None	V. Light	Light	Moderate	Mod./Heavy	Heavy	V. Heavy
DAMAGE	Vulnerable Structures	None	None	None	Light	Moderate	Mod./Heavy	Heavy	V. Heavy	V. Heavy

^{*}Estimated exposure only includes population within the map area.

Population Exposure

population per 1 sq. km from Landscan

Structures

Overall, the population in this region resides in structures that are a mix of vulnerable and earthquake resistant construction. The predominant vulnerable building types are adobe block and dressed stone/block masonry construction.

Historical Earthquakes

Date	Dist.	Mag.	Max	Shaking
(UTC)	(km)		MMI(#)	Deaths
2004-07-30	327	4.8	VI(2k)	1
1976-03-25	306	4.8	VI(1k)	1
1988-12-07	387	6.7	IX(50k)	25k

Recent earthquakes in this area have caused secondary hazards such as landslides that might have contributed to losses.

Selected City Exposure

from Ge	eoNames.org	
MMI	City	Population
VI	Can	<1k
V	Yayladere	4k
IV	Sancak	<1k
IV	Karakocan	30k
IV	Kasaba	<1k
IV	Dereova	<1k
Ш	Elazig	298k
Ш	Diyarbakir	645k
Ш	Erzurum	421k
Ш	Batman	382k
Ш	Malatya	442k

bold cities appear on map.

(k = x1000)

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	39.0°	E		40.5°E Caykara		42.0°E
40.4°N			mus'ıkhane		Ispir	Oltu Narman
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		Elazig		Bing J	Kulp	Mus
38.1°N	alatya		Ergani		Silvan	Bitlis
Ad	iyarıyan kn	Sivere	k	Diyarbakir	Batm	an
0	50	100) Si

PAGER content is automatically generated, and only considers losses due to structural damage. Limitations of input data, shaking estimates, and loss models may add uncertainty.